Cirrcullam Vitae

1).Name	:Dr.Rega Rajendra (OU ID-51020)			
2).Designation	: Professor			
3).Department/College : Mechanical Engineering, University College of Engineering				
4). Academic qualifications	: BE (Mech Engg), ME (Prod Engg), PhD (IITKGP)			
5).Specialization	: Production Engineering and Robotics			
6) UG Degree:	:BE, Mechanical Engineering Year: 1995 University: Osmania			
	University Class/Division: First Overall Percentage/CGPA: 65			
7) PG Degree: ME(Production Engineering) Year : 2003 University : Osmania University				
Class/Division: First Overall Percentage/CGPA: 65				

8).. PhD : IIT KGP- Title Modelling and Simulation of Robotic Systems

9).. Teaching Experience as on 01-08-2024: 27 Years 06 Months

10).. Industrial /Research Experience as on 19-10-2006: 00 Years 00 Months

(b).Papers Published in International/National Journal:

Rajendra, Rega., Pratihar D.K., Particle Swarm Optimization Algorithm vs. Genetic Algorithm to Develop Integrated Scheme for Obtaining Optimal Mechanical Structure and Adaptive Controller of a Robot", *Intelligent Control and Automation*, 2(4), pp. 430-449, 2011.

Rajendra, Rega., Pratihar D.K., "Particle Swarm Optimization Algorithm vs Genetic Algorithm to solve Multi-Objective Optimization in Gait Planning of Biped Robot", *Intl. Jl. of Control Engineering and Technology*, 1(2), pp.81-94, 2011.

i). Ambati Sainath, Rega Rajendra, Simulation of stress and forces on single point cutting tool on the onset of turning operation, *Peripex Indian Jl of Research*, pp.99-101, 2013.

ii).Uday Kiran K.L, Rajendra,Rega Comparative study on variation of process characteristics on Al and Die Steel components in sink EDM process, Vol-4(3), *Intl.Jl of Advanced Research in Engineering and Technology*, pp-170-177, 2013.

R. Rajendra, D.K. Pratihar, "Analysis of double support phase of biped robot and multi-objective optimization using genetic algorithm and particle swarm optimization algorithm," *Sadhana*

Goitom Tesfaye, Rega Rajendra; Global Form Deviation Evaluation of Free-form Surface using Coordinate Measuring Machine. International Journal of Mechanical and Production Engineering Research and Development, Vol. 7(6), 525-532, 2017. (Scopus indexed)

Goitom Tesfaye, Ravva Sirinivas, and Rega Rajendra; Equi-parametric Sampling Strategy for Evaluation of Higher Degree Free-form Surface using Contact Measurement. International Journal of advanced research in engineering & technology, Vol. 8(4), pp. 21–27, 2017. (Scopus indexed)

Goitom Tesfaye, T.S.S Prasad, Rega Rajendra; Isoparametric line Sampling Strategy for Evaluation of Lower Degree Free form surface using Contact Measurement. International Journal of Engineering and Manufacturing Science, Vol. 7(2), pp. 171-180, 2017. (UGC Recognized journal)

Goitom Tesfaye, Rega Rajendra; Adaptive sampling strategy of Free-form surface using CMM. Indian Academy of Science (Sadhana), Springer.(Communicated)

International Conferences:

Rajendra, Rega., Pratihar D.K., "Integrated Scheme for Optimization of Mechanical Structure and Controller of 2-DOF Manipulator Tracking Paths.", *Proc. of 5th Intl. Conf. on Theoretical, Applied, Computational and Experimental Mechanics (ICTACEM-2010)*, IIT, Kharagpur, 2010, pp. 186-188.

Rajendra, Rega., Pratihar D.K., "Particle Swarm Optimization Algorithm vs. Genetic Algorithm to Solve Multi-Objective Optimization Problem in Gait Planning of Biped Robot.", *Intl. Conf. on Information Systems Design and Intelligent Applications-2012 (InConINDIA-2012), Vishakhapatnam, India, 5-7, January, 2012, Advances in Intelligent and Soft computing 132, Springer*, pp. 563-570.

K.L.Uday Kiran^a, G.Chandramohan Reddy^b, A.M.K.Prasad^c, R.Rajendra^d; Study of Surface integrity Characteristics on Al and Die Steel Components using Copper tool in Sink EDM Process; 1st Intl. Conf. on Advances in Mechanical Sciences 2014 (ICAMS2014), 9-11 January,2014,Hyderabad, India, pp-191-197.

Chandrakanth Achelker^a, Srinivasa Rao N^b, G. Appala Raju^c, Rajendra R^d, Krishaniah.A^e, Performance Evaluation of Machine Tool Probe for On-Machine Measurement of 2D and 3D Geometries , *2nd International Conference on Innovations in Automation and Mechatronics Engineering*, (*ICIAME 2014*),7-8 March 2014,Anand,Gujrat,india,

Manasa Sala, Rajendra Rega "Performance Evaluation of Low Alloy Steel Welds for High Pressure Heater Shells "national conference on "**Recent Trends in Engineering & Science (RTES-2014**)" 2014. Indore 7-8, March,,pp.

Mohammed Anwar, Rega Rajendra, Influence of Metal Inert Gas Welding Speed on the Weld Bead Geometry of EN 10025 of S235JR Steel, national conference on **"Recent Trends in Engineering & Science (RTES-2014)**" 2014. Indore 7-8, March, ,pp.

Goitom Tesfaye, Rega Rajendra, Adaptive sampling strategy of Free-form surface using CMM. International conference on advanced materials and manufacturing 2016, Hyderabad, India.(Presented)

Goitom Tesfaye, Rega Rajendra, Sampling strategy of Free-form using Coordinate measuring machine surface, Indian Society of Mechanical Engineers 2017, NIT Warangal, India. (Presented)

Goitom Tesfaye, Rega Rajendra, Contour based adaptive sampling Strategy of Free-form surface using CMM, Proceeding of COPEN10 2017, IIT Madras chennai, 915-918. (Presented and Published ISBN: 978-93-80689-28-9.)

Goitom Tesfaye, Rega Rajendra, An Artefact Based Continues Performance Evaluation of CMM, 7th International and 28th All India Manufacturing Technology, Design And Research Conference 2018 (AIMTDR 2018)(Submitted).

C) Book Chapter

Goitom Tesfaye, Rega Rajendra, Sampling strategy of Free-form using Coordinate measuring machine surface, Mechanical Engineering for sustainable Development: State of the Art Research, Apple Academic press associated with CRC press, January 2018. (ISBN hard: 978-1-77188-681-9.)

Pratihar D.K., Pandu Ranga V., Rajendra R., Humanoid body control using neural networks and fuzzy logic, Springer Mateor: *Humanoid Robotics: a Reference, Neural Net and Fuzzy Logic Control* (accepted)

a). Book Published:

i). Principles of Engineering Metrology, Published by Jaico Publishing house, Mumbai, India, 2008, ISBN 978-3-659-26483-2

ii). **Modeling and Simulation of Robotic Systems using Soft Computing-** Lambert Academic Publishing, Germany, ISBN 978-3-659-26483-2

(c).Guiding/Supervision

Degree (M.Phil/PhD)	No.of Students	No.of Students	Degrees Awarded
	Registered	Completed	
PhD	08	02	02
ME(Master of Engg)	65	60	60

(e). National/International Seminars/Conference/Short Course/Workshops Conducted

i). **Conducted** A 3-day workshop on "**Metrology**" based on ASME Y14.5 GD&T for various College Faculty staff of Mechanical Engineering, at Mechanical Engineering Department, During March 21-23,2013, sponsored by TEQIP-II, funded MHRD, Govt. of India.

i). **Conducted** A 5-day Short Course on "**Knowledge Based Systems in Engineering** " based on ASME Y14.5 GD&T for various College Faculty staff of Mechanical Engineering, at Mechanical Engineering Department, During July 10-14,2013, sponsored by TEQIP-II, funded MHRD, Govt. of India.

i). **Conducted** A 5-day Short Course on "**Reverse Engineering based Manufacturing** "for various College Faculty staff of Mechanical Engineering, at Mechanical Engineering Department, During July 24-28,2013, sponsored by TEQIP-II, funded MHRD, Govt. of India.

(f). Major/Minor Research Projects: NIL

i). Completed-NIL

ii). On hand/New Projects: NIL

(g). Any other information -reminder

i).-Awarded PhD doctoral Degree in May 2012 by IITKharagpur under QIP scheme funded by

AICTE and sponsored by Osmania University.

NSS officer ,UCE(A), OU - one year

Asst Chief Wardent-Engg College Hostels, OU,

Warden, Swarnamukhi Hostel

Attend the Producvity Summit, 2006 at Chennai, Organsised by IMTMA

Attended Intl. Conf. Admet-2006, New Delhi on Adanceds on Metrolgy, organised by NPL, during

11-13 December,2006,

Life Member ISTAM -LM/252

ii) Faculty Advisor-for ME(Production Engineering) specialization during May 2003 (6 years) to May 2008 and from May 2011 to May 2013 (2 years).

"FORWARDED" /

SIGNATURE OF THE TEACHER

PRINCIPAL